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Fan Speed Controller - Author Glen Popiel - KW5GP

Based on OneWire Library - Copyright (c) 2007, Jim Studt (original old version - many contributors since)

The latest version of this library may be found at:
http://www.pjrc.com/teensy/td_libs_OneWire.html

OneWire has been maintained by Paul Stoffregen (paul@pjrc.com) since January 2010. At the time, it was in need of many bug fixes, but had been abandoned the original author (Jim Studt). None of the known contributors were interested in maintaining OneWire. Paul typically works on OneWire every 6 to 12 months. Patches usually wait that long. If anyone is interested in more actively maintaining OneWire, please contact Paul.

Version 2.2:

Teensy 3.0 compatibility, Paul Stoffregen, paul@pjrc.com
Arduino Due compatibility,
<http://arduino.cc/forum/index.php?topic=141030>
Fix DS18B20 example negative temperature
Fix DS18B20 example's low res modes, Ken Butcher
Improve reset timing, Mark Tillotson
Add const qualifiers, Bertrik Sikken
Add initial value input to crc16, Bertrik Sikken
Add target_search() function, Scott Roberts

Version 2.1:

Arduino 1.0 compatibility, Paul Stoffregen
Improve temperature example, Paul Stoffregen
DS250x_PROM example, Guillermo Lovato
PIC32 (chipKit) compatibility, Jason Dangel, dangel.jason AT gmail.com
Improvements from Glenn Trewitt:
- crc16() now works
- check_crc16() does all of calculation/checking work.
- Added read_bytes() and write_bytes(), to reduce tedious loops.
- Added ds2408 example.
Delete very old, out-of-date readme file (info is here)

Version 2.0: Modifications by Paul Stoffregen, January 2010:

http://www.pjrc.com/teensy/td_libs_OneWire.html
Search fix from Robin James
<http://www.arduino.cc/cgi-bin/yabb2/YaBB.pl?num=1238032295/27#27>
Use direct optimized I/O in all cases
Disable interrupts during timing critical sections
(this solves many random communication errors)
Disable interrupts during read-modify-write I/O
Reduce RAM consumption by eliminating unnecessary
variables and trimming many to 8 bits
Optimize both crc8 - table version moved to flash

Modified to work with larger numbers of devices - avoids loop.

Tested in Arduino 11 alpha with 12 sensors.

26 Sept 2008 -- Robin James

<http://www.arduino.cc/cgi-bin/yabb2/YaBB.pl?num=1238032295/27#27>

Updated to work with arduino-0008 and to include skip() as of
2007/07/06. --RJL20

Modified to calculate the 8-bit CRC directly, avoiding the need for
the 256-byte lookup table to be loaded in RAM. Tested in arduino-0010
-- Tom Pollard, Jan 23, 2008

Jim Studt's original library was modified by Josh Larios.

Tom Pollard, pollard@alum.mit.edu, contributed around May 20, 2008

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OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION
WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.

Much of the code was inspired by Derek Yerger's code, though I don't
think much of that remains. In any event that was..

(copyleft) 2006 by Derek Yerger - Free to distribute freely.

The CRC code was excerpted and inspired by the Dallas Semiconductor
sample code bearing this copyright.

```
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----  
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*/

```

```

#include <OneWire.h>    // Include the OneWire Library

#define temp_sensor 10  // Temperature Sensor attached to Pin 10
#define red 7          // Red LED on pin 7
#define blue 8          // Blue LED on pin 8
#define green 9         // Green LED on pin 9
#define fan 6           // Fan drive on pin 6
#define alarm 5         // alarm buzzer on pin 5
#define low_temp 80     // temperature to start fan
#define high_temp 95    // temperature to turn fan on full
#define alarm_temp 110  // alarm temperature

int DS18S20_Pin = temp_sensor; //DS18S20 Signal pin on temp_sensor pin

//Temperature chip I/O
OneWire ds(DS18S20_Pin); // on temp_sensor pin

void setup(void)
{
  for (int x = 5; x <=9; x++) // Set the Pin Modes for Pins 5 through 9
  {
    pinMode(x, OUTPUT);
    if (x <= 6) // For pins 5 and 6 start Low, 7-9 start High (LED off)
    {
      digitalWrite(x, LOW);
    } else {
      digitalWrite(x, HIGH);
    }
  }
}

```

```

    ledOff(); // Turn LED Off if below low_temp
}

void loop(void)
{
    float temperature = getTemp(); // Read the Temperature Sensor
    if (temperature < low_temp) // Everything off if below low_temp
    {
        ledOff();
        digitalWrite(fan, LOW);
        digitalWrite(alarm, LOW);
    }
    if (temperature >= low_temp && temperature <= high_temp) // Run the
Fan as a proportion of the temp
    {
        analogWrite(fan, map(temperature, low_temp, high_temp, 30, 255)); //
Starting PWM should be 30 or above to prevent fan stall
        ledBlue(); // Indicate Fan Running - Temp within range
        // Turn on the fan at slow speed
    }
    if (temperature > high_temp && temperature < alarm_temp) // Turn the
Fan on full speed
    {
        analogWrite(fan, 255); // Set the Fan to Max Speed
        ledGreen(); // Indicate Fan Running - Max Speed
    }
    if (temperature >= alarm_temp) // Overtemp Alarm
    {
        ledRed(); // Indicate Temp over Limit
        digitalWrite(alarm, HIGH); // Sound the Alarm
    } else {
        digitalWrite(alarm, LOW);
    }
}

// ----- Functions -----
-----

float getTemp() //returns the temperature from one DS18S20 in DEG
Fahrenheit
{
    byte data[12];
    byte addr[8];

    if ( !ds.search(addr)) // Look for more sensors
    {
        //no more sensors on chain, reset search
        ds.reset_search();
        return -1000;
    }

    if ( OneWire::crc8( addr, 7) != addr[7]) // Check the CRC
    {

```

```

        return -1000;
    }

    if ( addr[0] != 0x10 && addr[0] != 0x28) // Verify the Device type
    {
        return -1000;
    }

    ds.reset();
    ds.select(addr);
    // ds.write(0x44,1); // start conversion, with parasite power on at
the end
    ds.write(0x44); // start conversion, without parasite power on at the
end

    byte present = ds.reset();
    ds.select(addr);
    ds.write(0xBE); // Read Scratchpad

    for (int i = 0; i < 9; i++)
    { // we need 9 bytes
        data[i] = ds.read();
    }

    ds.reset_search();

    byte MSB = data[1]; // Split the data into MSB and LSB
    byte LSB = data[0];

    float tempRead = ((MSB << 8) | LSB); //using two's compliment
    float Centigrade = tempRead / 16; // Calculate temperature in
Centigrade
    float Farenheit = Centigrade * 1.8 + 32.0; // Convert from Centigrade
to Farenheit

    return Farenheit; // Return Farenheit - Can be changed to return
Centigrade if desired
}

// LED Off function
void ledOff()
{
    digitalWrite(red, HIGH); // Set all RGB LED pins High (Off)
    digitalWrite(green, HIGH);
    digitalWrite(blue, HIGH);
}

// RED LED ON function
void ledRed()
{
    digitalWrite(red, LOW); // Turn on the RGB Red LED On

```

```
    digitalWrite(green, HIGH);
    digitalWrite(blue, HIGH);
}

// Green LED ON function
void ledGreen()
{
    digitalWrite(red, HIGH);
    digitalWrite(green, LOW); // Turn on the RGB Green LED On
    digitalWrite(blue, HIGH);
}

// Blue LED ON function
void ledBlue()
{
    digitalWrite(red, HIGH);
    digitalWrite(green, HIGH);
    digitalWrite(blue, LOW); // Turn on the RGB Blue LED On
}
```